

Unique Common Tripled Fixed Point for Three Mappings in \mathcal{G}_b -metric Spaces

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Abstract It has been a century since the Banach fixed point theorem was established, and because of this, the result is the progenitor in some ways. This seems essential to revisit fixed point theorems in specific and in light of most of those. Those are numerous and prevalent in mathematics, as we will demonstrate. Fixed point theorems can be noticed in advanced mathematics, economics, micro-structures, geometry, dynamics, computational mathematics, and differential equations. \mathcal{G} -metric space is the broaden and extrapolate the paradigm of the concept of metric space. The characteristic of a \mathcal{G} -metric space, in essence, is to comprehend the topological features of three points rather than two points via the perimeter of a triangle, where the metric indicates the distance between two points. The domain of \mathcal{G}_b -metric space is significantly larger than that of the class of \mathcal{G} -metric space. Hence we utilised this generalized space in order to obtain common tripled fixed point for three mappings using rational type contractions in the setting of \mathcal{G}_b -metric spaces. Recently, Khomadram et al have developed coupled fixed point theorems in \mathcal{G}_b -metric spaces via rational type contractions. The main aim of our paper is to broaden and extrapolate the paradigm of Khomadram's results into tripled fixed point theorems. Therefore, examples are offered to support our findings.

Keywords \mathcal{G}_b -metric Space, \mathcal{G}_b -Cauchy Sequence, \mathcal{G}_b -convergent Sequence and Tripled Fixed Point

1 Introduction

"Topological metric space theory" originates from the vast area of non-linear functional analysis. Fixed point theorem is a qualitative result which concerns with finding conditions on the frame of a non-empty set and the choice of mapping on that particular set, in order to obtain a fixed point usually. Many problems in problems in engineering and applied sciences are made usually in the structure of differential and integral equations. Fixed

point theorems discover many applications in proving the existence of unique solutions for various existed differential and integral equations that appear in the study of problems in heat and mass transfer, fluid mechanics, chemical and electrochemical process, molecular physics and in many other fields.

Initially in 1909, Frechet[10] introduced the notion of metric as a distance function. In 1989, Bakhtin[5] introduced the concept of b -metric space as a generalization of metric space. Mustafa and Sims [20] led to the enactment of \mathcal{G} -metric space in 2006 to broaden and extrapolate the paradigm of metric space. In assertion, understanding the geometric features of three points rather than two points through the use of the perimeter of a triangle is the characteristic of a \mathcal{G} -metric space. In 2014, Aghajani et al[2]introduced a \mathcal{G}_b -metric space as a different generalization of metric space using the concepts of b -metric space and \mathcal{G} -metric space.

The goal of this study is to show that unique common tripled fixed point theorems for three mappings via rational type contractive conditions which are broaden and extrapolate the paradigm of the results of Khomadram et al [14] in the setting of \mathcal{G}_b -metric spaces. Metric spaces are the medium where a significant amount of functional analysis ideas and conclusions are articulated. This article on \mathcal{G} -metric space appears to skim through the fundamentals of the problem so very rapidly. The authors of this paper aim to take a relaxed approach to the theory of \mathcal{G} -metric spaces. The following definitions and propositions are used to derive our main results.

Definition 1.1 ([2]) Let \mathcal{M} be a nonempty set and $\mathcal{G}_b : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow \mathbb{R}$ and $s \geq 1$ be a real number such that

$$(\mathcal{G}1) \quad \mathcal{G}_b(a, b, c) \geq 0 \text{ for all } a, b, c \in \mathcal{M} \text{ with } \mathcal{G}_b(a, b, c) = 0 \text{ if } a = b = c,$$

$$(\mathcal{G}2) \quad \mathcal{G}_b(a, a, b) > 0 \text{ for all } a, b \in \mathcal{M} \text{ with } a \neq b,$$

$$(\mathcal{G}3) \quad \mathcal{G}_b(a, a, b) \leq \mathcal{G}_b(a, b, c) \text{ for all } a, b, c \in \mathcal{M} \text{ with } c \neq b,$$

$$(\mathcal{G}4) \quad \mathcal{G}_b(a, b, c) = \mathcal{G}_b(a, c, b) = \mathcal{G}_b(b, a, c) = \mathcal{G}_b(c, a, b) = \mathcal{G}_b(b, c, a) = \mathcal{G}_b(c, b, a) \\ \text{for all } a, b, c \in \mathcal{M}$$

$$(\mathcal{G}5) \quad \mathcal{G}_b(a, b, c) \leq s[\mathcal{G}_b(a, w, w) + \mathcal{G}_b(w, b, c)] \text{ for all } a, b, c, w \in \mathcal{M}$$

Then the pair $(\mathcal{M}, \mathcal{G}_b)$ is called a \mathcal{G}_b -metric space with \mathcal{G}_b -metric \mathcal{G}_b on \mathcal{M} . Axioms $(\mathcal{G}4)$ and $(\mathcal{G}5)$ are referred to as the *symmetry* and the *rectangle inequality* (of \mathcal{G}_b) respectively.

Given a \mathcal{G}_b -metric space $(\mathcal{M}, \mathcal{G}_b)$, define

$$\rho_{\mathcal{G}}(a, b) = \mathcal{G}_b(a, b, b) + \mathcal{G}_b(a, a, b) \text{ for all } a, b, c \in \mathcal{M}. \quad (1.1)$$

Then it is seen in [2] that $\rho_{\mathcal{G}}$ is a b -metric on \mathcal{M} and that the family of all \mathcal{G}_b -balls $\{B_{\mathcal{G}}(a, r) : a \in \mathcal{M}, r > 0\}$ is the base topology, called the \mathcal{G}_b -metric topology $\tau(\mathcal{G}_b)$ on \mathcal{M} , where $B_{\mathcal{G}}(a, r) = \{b \in \mathcal{M} : \mathcal{G}_b(a, b, b) < r\}$. Further, it was shown that the \mathcal{G}_b -metric topology coincides with the metric topology induced by the b -metric $\rho_{\mathcal{G}}$, this enables us to convert numerous notions form b -metric to \mathcal{G}_b -metric space with ease.

Definition 1.2 ([2]) A \mathcal{G}_b -metric space $(\mathcal{M}, \mathcal{G}_b)$ is said to be symmetric if $\mathcal{G}_b(a, b, b) = \mathcal{G}_b(b, a, a)$ for all $a, b \in \mathcal{M}$.

Definition 1.3 ([2]) A sequence $\langle a_\sigma \rangle$ in a \mathcal{G}_b -metric space $(\mathcal{M}, \mathcal{G}_b)$ is said to be \mathcal{G}_b -convergent to $a \in \mathcal{M}$ if for every $\epsilon > 0$ there is a positive integer N such that $\mathcal{G}_b(a_\sigma, a_\xi, a) < \epsilon$ for all $\xi, \sigma \geq N$.

Proposition 1.1. ([2]) Let $(\mathcal{M}, \mathcal{G}_b)$ be a \mathcal{G}_b -metric space. Then the followings are equivalent.

- (i) $\langle a_\sigma \rangle_{\sigma=1}^{\infty}$ is \mathcal{G}_b -convergent to a
- (ii) $\mathcal{G}_b(a_\sigma, a_\sigma, a) \rightarrow 0$ as $\sigma \rightarrow \infty$
- (iii) $\mathcal{G}_b(a_\sigma, a, a) \rightarrow 0$ as $\sigma \rightarrow \infty$.

Definition 1.4 ([2]) A sequence $\langle a_\sigma \rangle$ in a \mathcal{G}_b -metric space $(\mathcal{M}, \mathcal{G}_b)$ is said to be \mathcal{G}_b -Cauchy if for every $\epsilon > 0$ there is a positive integer N such that $\mathcal{G}_b(x_\sigma, x_\xi, x_\eta) < \epsilon$ for all $\sigma, \xi, \eta \geq N$.

Proposition 1.2. ([2]) Let $(\mathcal{M}, \mathcal{G}_b)$ be a \mathcal{G}_b -metric space. Then followings are equivalent.

- (i) $\langle a_\sigma \rangle$ is \mathcal{G}_b -Cauchy.
- (ii) for every $\epsilon > 0$ there is a positive integer N such that $\mathcal{G}_b(a_\sigma, a_\xi, a_\xi) < \epsilon$ for all $\xi, \sigma \geq N$.

Proposition 1.3. ([2]) Every \mathcal{G}_b -convergent sequence in a \mathcal{G}_b -metric space $(\mathcal{M}, \mathcal{G}_b)$ is \mathcal{G}_b -Cauchy.

Definition 1.5 ([2]) A \mathcal{G}_b -metric space $(\mathcal{M}, \mathcal{G}_b)$ is said to be \mathcal{G}_b -complete if every \mathcal{G}_b -Cauchy sequence in \mathcal{M} converges in it.

Proposition 1.4. ([2]) Let $(\mathcal{M}, \mathcal{G}_b)$ be a \mathcal{G}_b -metric space. A mapping $g : \mathcal{M} \rightarrow \mathcal{M}$ is \mathcal{G}_b -continuous at $a \in \mathcal{M}$ if and only if the sequence $\langle ga_\sigma \rangle$ converges to ga whenever $\langle a_\sigma \rangle$ converges to a .

Proposition 1.5. ([2]) The \mathcal{G}_b -metric $\mathcal{G}_b(a, b, c)$ is jointly continuous in all the three variables a, b and c .

Proposition 1.6. ([2]) If $(\mathcal{M}, \mathcal{G}_b)$ is a \mathcal{G}_b -metric space, then it follows that

- (i) if $\mathcal{G}_b(a, b, c) = 0$ then $a = b = c$;
- (ii) $\mathcal{G}_b(a, b, c) \leq s[\mathcal{G}_b(a, a, b) + \mathcal{G}_b(a, a, c)]$;
- (iii) $\mathcal{G}_b(a, b, b) \leq 2s\mathcal{G}_b(b, a, a)$;
- (iv) $\mathcal{G}_b(a, b, c) \leq s[\mathcal{G}_b(a, x, c) + \mathcal{G}_b(x, b, c)]$ for all $a, b, c, x \in \mathcal{M}$.

Samet and Vetro [23] introduced a fixed point of order $N \geq 3$ in the year 2010. The following is the definition of fixed point of order 3.

Definition 1.6 ([23]) Let \mathcal{M} be a nonempty set. An element (a, b, c) in $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$ is said to be tripled fixed point of a mapping $\mathcal{S} : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow \mathcal{M}$, if $\mathcal{S}(a, b, c) = a, \mathcal{S}(b, a, c) = b$ and $\mathcal{S}(c, a, b) = b$.

Definition 1.7 ([23]) An element (a, b, c) in $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$ is said to be common tripled fixed point of mappings \mathcal{S}, \mathcal{T} and \mathcal{R} on $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$, if $\mathcal{S}(a, b, c) = \mathcal{T}(a, b, c) = \mathcal{R}(a, b, c) = a, \mathcal{S}(b, a, c) = \mathcal{T}(b, a, c) = \mathcal{R}(b, a, c) = b$ and $\mathcal{S}(c, a, b) = \mathcal{T}(c, a, b) = \mathcal{R}(c, a, b) = c$.

In 2011, Berinde and Borcut [6] defined another notion of a tripled fixed point for mappings which are satisfying mixed monotone property in partially ordered metric spaces.

2 Main Results

Theorem 2.1 Let $(\mathcal{M}, \mathcal{G}_b)$ be a complete symmetric \mathcal{G}_b -metric space with parameter $s \geq 1$ and $\mathcal{S}, \mathcal{T}, \mathcal{R} : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow \mathcal{M}$ be three mappings such that

$$\begin{aligned}
 & \mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) \\
 & \leq \mathbb{K}_1 \frac{\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}{3} \\
 & + \mathbb{K}_2 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}, \\
 & + \mathbb{K}_3 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 & + \mathbb{K}_4 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 & + \mathbb{K}_5 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 & + \mathbb{K}_6 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}
 \end{aligned}
 \tag{2.1}$$

$$\begin{aligned}
& + \mathbb{K}_7 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
& + \mathbb{K}_8 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
& + \mathbb{K}_9 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
& + \mathbb{K}_{10} \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
& + \mathbb{K}_{11} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
& + \mathbb{K}_{12} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
& + \mathbb{K}_{13} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}
\end{aligned}$$

for all $x, y, z, \lambda, \kappa, \zeta, \nu, \iota, \wp \in \mathcal{M}$ and non negative real numbers $\mathbb{K}_1, \mathbb{K}_2, \mathbb{K}_3, \mathbb{K}_4, \mathbb{K}_5, \mathbb{K}_6, \mathbb{K}_7, \mathbb{K}_8, \mathbb{K}_9, \mathbb{K}_{10}, \mathbb{K}_{11}, \mathbb{K}_{12}, \mathbb{K}_{13}$ with $0 \leq \mathbb{K}_1 + \mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + 3(\mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7) + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13} < 1$. Then \mathcal{S}, \mathcal{T} and \mathcal{R} have a unique common tripled fixed point in \mathcal{M} .

Proof. Let x_0, y_0 and z_0 be any three elements in \mathcal{M} . We construct three sequences $\langle x_\sigma \rangle_{\sigma=1}^\infty, \langle y_\sigma \rangle_{\sigma=1}^\infty$ and $\langle z_\sigma \rangle_{\sigma=1}^\infty$ in \mathcal{M} as follows:

$$\begin{aligned}
x_{3\phi+1} &= \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}), y_{3\phi+1} = \mathcal{S}(y_{3\phi}, z_{3\phi}, x_{3\phi}), z_{3\phi+1} = \mathcal{S}(z_{3\phi}, x_{3\phi}, y_{3\phi}) \\
x_{3\phi+2} &= \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}), y_{3\phi+2} = \mathcal{T}(y_{3\phi+1}, z_{3\phi+1}, x_{3\phi+1}), z_{3\phi+2} = \mathcal{T}(z_{3\phi+1}, x_{3\phi+1}, y_{3\phi+1}) \\
x_{3\phi+3} &= \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2}), y_{3\phi+3} = \mathcal{R}(y_{3\phi+2}, z_{3\phi+2}, x_{3\phi+2}), z_{3\phi+3} = \mathcal{R}(z_{3\phi+2}, x_{3\phi+2}, y_{3\phi+2}) \\
&\text{for } \phi = 0, 1, 2, 3, \dots
\end{aligned}$$

Now using (2.1) with $x = x_{3\phi}, y = y_{3\phi}, z = z_{3\phi}, \lambda = x_{3\phi+1}, \kappa = y_{3\phi+1}, \zeta = z_{3\phi+1}, \nu = x_{3\phi+2}, \iota = y_{3\phi+2}$ and $\wp = z_{3\phi+2}$, we get

$$\begin{aligned}
& \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) = \mathcal{G}_b(\mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}), \mathcal{S}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}), \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \\
& \leq \mathbb{K}_1 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}{3} \\
& + \mathbb{K}_2 \frac{\mathcal{G}_b(\mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}), \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}), \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \cdot \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})} \\
& + \mathbb{K}_3 \frac{\mathcal{G}_b(\mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}), \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}), \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \cdot \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})} \\
& + \mathbb{K}_4 \frac{\mathcal{G}_b(\mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}), \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}), \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \cdot \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})} \\
& + \mathbb{K}_5 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi}, \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi})) \cdot \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})} \\
& + \mathbb{K}_6 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi}, \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi})) \cdot \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})} \\
& + \mathbb{K}_7 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi}, \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi})) \cdot \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})} \\
& + \mathbb{K}_8 \frac{\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1})) \cdot \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})} \\
& + \mathbb{K}_9 \frac{\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1})) \cdot \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2})}{1 + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}
\end{aligned}$$

$$+ (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4) \cdot \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) + (\mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7) \cdot \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) \\ + (\mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13}) \cdot \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3})$$

so that

$$\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) \leq \frac{\frac{\mathbb{K}_1}{3} + \mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \frac{\frac{\mathbb{K}_1}{3}}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \frac{\frac{\mathbb{K}_1}{3}}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2}) \quad (2.2)$$

Similarly,

$$\mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) \leq \frac{\frac{\mathbb{K}_1}{3} + \mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \frac{\frac{\mathbb{K}_1}{3}}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \frac{\frac{\mathbb{K}_1}{3}}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2}) \quad (2.3)$$

and

$$\mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3}) \leq \frac{\frac{\mathbb{K}_1}{3} + \mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2}) + \frac{\frac{\mathbb{K}_1}{3}}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \frac{\frac{\mathbb{K}_1}{3}}{[1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})]} \\ \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) \quad (2.4)$$

Adding (2.2),(2.3) and (2.4),we have

$$\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) + \mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) + \mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3}) \\ \leq \frac{\mathbb{K}_1 + 3(\mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7)}{1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})} \\ [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})].$$

or

$$\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) + \mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) + \mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3}) \\ \leq c \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]. \quad (2.5)$$

where $c = \frac{\mathbb{K}_1 + 3(\mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7)}{1 - (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13})}$ and $0 \leq c < 1$ in view of choice of $\mathbb{K}_1, \mathbb{K}_2, \mathbb{K}_3, \mathbb{K}_4, \mathbb{K}_5, \mathbb{K}_6, \mathbb{K}_7, \mathbb{K}_8, \mathbb{K}_9, \mathbb{K}_{10}, \mathbb{K}_{11}, \mathbb{K}_{12}$ and \mathbb{K}_{13} .

Also, it can be proved that

$$\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+3}, x_{3\phi+4}) + \mathcal{G}_b(y_{3\phi+2}, y_{3\phi+3}, y_{3\phi+4}) + \mathcal{G}_b(z_{3\phi+2}, z_{3\phi+3}, z_{3\phi+4})$$

$$\begin{aligned} &\leq c \cdot [\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) + \mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) + \mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3})]. \\ &\leq c^2 \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]. \end{aligned}$$

Proceeding like this, we get

$$\begin{aligned} &\mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+2}) + \mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+2}) + \mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+2}) \\ &\leq c \cdot [\mathcal{G}_b(x_{\sigma-1}, x_\sigma, x_{\sigma+1}) + \mathcal{G}_b(y_{\sigma-1}, y_\sigma, y_{\sigma+1}) + \mathcal{G}_b(z_{\sigma-1}, z_\sigma, z_{\sigma+1})]. \\ &\leq c^2 \cdot [\mathcal{G}_b(x_{\sigma-2}, x_{\sigma-1}, x_\sigma) + \mathcal{G}_b(y_{\sigma-2}, y_{\sigma-1}, y_\sigma) + \mathcal{G}_b(z_{\sigma-2}, z_{\sigma-1}, z_\sigma)]. \\ &\vdots \\ &\leq c^\sigma \cdot [\mathcal{G}_b(x_0, x_1, x_2) + \mathcal{G}_b(y_0, y_1, y_2) + \mathcal{G}_b(z_0, z_1, z_2)] \text{ where } \sigma = 3\phi + 2. \end{aligned}$$

Let $\Delta_\sigma = \mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+2}) + \mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+2}) + \mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+2})$. Then the above inequality becomes as $\Delta_\sigma \leq c\Delta_{\sigma-1} \leq c^2\Delta_{\sigma-2} \leq \dots \leq c^\sigma\Delta_0$ for $\sigma \in \mathbb{N}$

Suppose $\xi > \sigma$. Now using repeated application of rectangle inequality of \mathcal{G}_b -metric and the inequality $\Delta_\sigma \leq c^\sigma\Delta_0$, we have

$$\begin{aligned} &\mathcal{G}_b(x_\sigma, x_\xi, x_\xi) + \mathcal{G}_b(y_\sigma, y_\xi, y_\xi) + \mathcal{G}_b(z_\sigma, z_\xi, z_\xi) \leq s[\mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+1}) + \mathcal{G}_b(x_{\sigma+1}, x_\xi, x_\xi)] \\ &\quad + s[\mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+1}) + \mathcal{G}_b(y_{\sigma+1}, y_\xi, y_\xi)] + s[\mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+1}) + \mathcal{G}_b(z_{\sigma+1}, z_\xi, z_\xi)] \\ &\leq s[\mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+1}) + \mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+1}) + \mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+1})] \\ &\quad + s^2[\mathcal{G}_b(x_{\sigma+1}, x_{\sigma+2}, x_{\sigma+2}) + \mathcal{G}_b(y_{\sigma+1}, y_{\sigma+2}, y_{\sigma+2}) + \mathcal{G}_b(z_{\sigma+1}, z_{\sigma+2}, z_{\sigma+2})] \\ &\quad + \dots + s^{\xi-\sigma}[\mathcal{G}_b(x_{\xi-1}, x_{\xi-1}, x_\xi) + \mathcal{G}_b(y_{\xi-1}, y_{\xi-1}, y_\xi) + \mathcal{G}_b(z_{\xi-1}, z_{\xi-1}, z_\xi)] \\ &= s\Delta_\sigma + s^2\Delta_{\sigma+1} + s^3\Delta_{\sigma+2} + \dots + s^{\xi-\sigma}\Delta_{\xi-1} \\ &\leq [sc^\sigma + s^2c^{\sigma+1} + \dots + s^{\xi-\sigma}c^{\xi-1}]\Delta_0 \\ &\leq sc^\sigma \cdot \frac{1}{1-c}\Delta_0 \text{ for } \xi > \sigma \end{aligned}$$

or

$$\mathcal{G}_b(x_\sigma, x_\xi, x_\xi) + \mathcal{G}_b(y_\sigma, y_\xi, y_\xi) + \mathcal{G}_b(z_\sigma, z_\xi, z_\xi) \leq s \cdot c^\sigma \cdot \frac{1}{1-c}\Delta_0 \text{ for } \xi > \sigma. \tag{2.6}$$

Since $0 \leq c < 1, c^\sigma \rightarrow 0$ as $\sigma \rightarrow \infty$.

Now applying limit as $\sigma \rightarrow \infty$ with $\xi > \sigma$ in the inequality (2.6), we have

$\mathcal{G}_b(x_\sigma, x_\xi, x_\xi) + \mathcal{G}_b(y_\sigma, y_\xi, y_\xi) + \mathcal{G}_b(z_\sigma, z_\xi, z_\xi) \leq 0$ which follows that $\langle x_\sigma \rangle_{\sigma=1}^\infty, \langle y_\sigma \rangle_{\sigma=1}^\infty$ and $\langle z_\sigma \rangle_{\sigma=1}^\infty$ are \mathcal{G}_b -Cauchy sequences in \mathcal{M} .

Since $(\mathcal{M}, \mathcal{G}_b)$ is a complete \mathcal{G}_b -metric space, there exist $x, y, z \in \mathcal{M}$ such that $x_\sigma \rightarrow x, y_\sigma \rightarrow y$ and $z_\sigma \rightarrow z$ as $\sigma \rightarrow \infty$.

Now we prove that (x, y, z) is a tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} .

Again using (2.1) with $x = x_\sigma, y = y_\sigma, z = z_\sigma, \sigma = x, \kappa = y, \zeta = z, \nu = x, \iota = y$ and $\wp = z$, we get

$$\begin{aligned} &\mathcal{G}_b(x, \mathcal{S}(x, y, z), \mathcal{S}(x, y, z)) \leq s[\mathcal{G}_b(x, x_{\sigma+1}, x_{\sigma+1}) + \mathcal{G}_b(x_{\sigma+1}, \mathcal{S}(x, y, z), \mathcal{S}(x, y, z))] \tag{2.7} \\ &\leq s\mathcal{G}_b(x, x_{\sigma+1}, x_{\sigma+1}) + s \left[\frac{\mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)}{3} \right. \\ &\quad + \mathbb{K}_2 \frac{\mathcal{G}_b(\mathcal{S}(x_\sigma, x, x), \mathcal{S}(y_\sigma, y, y), \mathcal{S}(z_\sigma, z, z)) \cdot \mathcal{G}_b(x_\sigma, x, x)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\ &\quad + \mathbb{K}_3 \frac{\mathcal{G}_b(\mathcal{S}(x_\sigma, x, x), \mathcal{S}(y_\sigma, y, y), \mathcal{S}(z_\sigma, z, z)) \cdot \mathcal{G}_b(y_\sigma, y, y)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\ &\quad + \mathbb{K}_4 \frac{\mathcal{G}_b(\mathcal{S}(x_\sigma, x, x), \mathcal{S}(y_\sigma, y, y), \mathcal{S}(z_\sigma, z, z)) \cdot \mathcal{G}_b(z_\sigma, z, z)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\ &\quad \left. + \mathbb{K}_5 \frac{\mathcal{G}_b(x_\sigma, x_\sigma, \mathcal{S}(x_\sigma, y_\sigma, z_\sigma)) \cdot \mathcal{G}_b(x_\sigma, x, x)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \right] \end{aligned}$$

$$\begin{aligned}
 &+ \mathbb{K}_6 \frac{\mathcal{G}_b(x_\sigma, x_\sigma, \mathcal{S}(x_\sigma, y_\sigma, z_\sigma)) \cdot \mathcal{G}_b(y_\sigma, y, y)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\
 &+ \mathbb{K}_7 \frac{\mathcal{G}_b(x_\sigma, x_\sigma, \mathcal{S}(x_\sigma, y_\sigma, z_\sigma)) \cdot \mathcal{G}_b(z_\sigma, z, z)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\
 &+ \mathbb{K}_8 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x_\sigma, x, x)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\
 &+ \mathbb{K}_9 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(y_\sigma, y, y)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\
 &+ \mathbb{K}_{10} \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(z_\sigma, z, z)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\
 &+ \mathbb{K}_{11} \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x_\sigma, x, x)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\
 &+ \mathbb{K}_{12} \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(y_\sigma, y, y)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \\
 &+ \mathbb{K}_{13} \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(z_\sigma, z, z)}{1 + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)} \Big]
 \end{aligned}$$

Since $x_\sigma \rightarrow x, y_\sigma \rightarrow y$ and $z_\sigma \rightarrow z$, from the inequality(2.7) it follows that $\mathcal{G}_b(x, \mathcal{S}(x, y, z), \mathcal{S}(x, y, z)) = 0$ which implies that $\mathcal{S}(x, y, z) = x$ and also $\mathcal{S}(y, x, z) = y, \mathcal{S}(z, x, y) = z$.

Similarly, it can be shown that $\mathcal{T}(x, y, z) = x, \mathcal{T}(y, x, z) = y, \mathcal{T}(z, x, y) = z, \mathcal{R}(x, y, z) = x, \mathcal{R}(y, x, z) = y$ and $\mathcal{R}(z, x, y) = z$.

That is (x, y, z) is a common tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} .

Uniqueness:

Suppose (l, m, n) is another common tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} .

That is, $\mathcal{S}(l, m, n) = \mathcal{T}(l, m, n) = \mathcal{R}(l, m, n) = l, \mathcal{S}(m, l, n) = \mathcal{T}(m, l, n) = \mathcal{R}(m, l, n) = m$ and $\mathcal{S}(n, l, m) = \mathcal{T}(n, l, m) = \mathcal{R}(n, l, m) = n$

Using inequality(2.1), we have

$$\begin{aligned}
 \mathcal{G}_b(x, l, l) &= \mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(l, m, n), \mathcal{R}(l, m, n)) \\
 &\leq \mathbb{K}_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} \\
 &+ \mathbb{K}_2 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(l, m, n), \mathcal{R}(l, m, n)) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_3 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(l, m, n), \mathcal{R}(l, m, n)) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_4 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(l, m, n), \mathcal{R}(l, m, n)) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_5 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_6 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_7 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_8 \frac{\mathcal{G}_b(l, l, \mathcal{T}(l, m, n)) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_9 \frac{\mathcal{G}_b(l, l, \mathcal{T}(l, m, n)) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 &+ \mathbb{K}_{10} \frac{\mathcal{G}_b(l, l, \mathcal{T}(l, m, n)) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}
 \end{aligned}$$

$$\begin{aligned}
 & + \mathbb{K}_{11} \frac{\mathcal{G}_b(l, l, \mathcal{R}(l, m, n)) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_{12} \frac{\mathcal{G}_b(l, l, \mathcal{R}(l, m, n)) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_{13} \frac{\mathcal{G}_b(l, l, \mathcal{R}(l, m, n)) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 = & \mathbb{K}_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} + \mathbb{K}_2 \frac{\mathcal{G}_b(x, l, l) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_3 \frac{\mathcal{G}_b(x, l, l) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_4 \frac{\mathcal{G}_b(x, l, l) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_5 \frac{\mathcal{G}_b(x, x, x) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_6 \frac{\mathcal{G}_b(x, x, x) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_7 \frac{\mathcal{G}_b(x, x, x) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_8 \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_9 \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_{10} \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_{11} \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(x, l, l)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_{12} \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(y, m, m)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)} \\
 & + \mathbb{K}_{13} \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(z, n, n)}{1 + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}
 \end{aligned}$$

which implies

$$\mathcal{G}_b(x, l, l) \leq \mathbb{K}_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} + (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4) \mathcal{G}_b(x, l, l) \tag{2.8}$$

Similarly

$$\mathcal{G}_b(y, m, m) \leq \mathbb{K}_1 \frac{\mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n) + \mathcal{G}_b(x, l, l)}{3} + (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4) \mathcal{G}_b(y, m, m) \tag{2.9}$$

and

$$\mathcal{G}_b(z, n, n) \leq \mathbb{K}_1 \frac{\mathcal{G}_b(z, n, n) + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m)}{3} + (\mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4) \mathcal{G}_b(z, n, n) \tag{2.10}$$

Adding (2.8),(2.9) and (2.10), we get

$$\begin{aligned}
 \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n) & \leq (\mathbb{K}_1 + \mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4) [\mathcal{G}_b(x, l, l) \\
 & \quad + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)]
 \end{aligned}$$

or

$$(1 - \mathbb{K}_1 - \mathbb{K}_2 - \mathbb{K}_3 - \mathbb{K}_4)\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n) \leq 0 \quad (2.11)$$

Since $\mathbb{K}_1 + \mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 < 1$, we have $\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n) = 0$ which implies that $x = l, y = m$ and $z = n$.

Thus, (x, y, z) is a unique common tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} . \square

Example 2.1. Let $\mathcal{M} = [0, 1]$. Define $\mathcal{G}_b : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow [0, \infty)$ by $\mathcal{G}_b(\alpha, \beta, \gamma) = (|\alpha - \beta| + |\beta - \gamma| + |\gamma - \alpha|)^2$, where $s = 2$. Clearly, $(\mathcal{M}, \mathcal{G}_b)$ is a complete \mathcal{G}_b -metric space.

Let $\mathcal{S}(x, y, z) = \frac{2x-4y+6z+20}{24}, \mathcal{T}(\lambda, \kappa, \zeta) = \frac{3\lambda-6\kappa+9\zeta+30}{36}$ and

$\mathcal{R}(\nu, \iota, \wp) = \frac{4\nu-8\iota+12\wp+40}{48}$ for $x, y, z, \lambda, \kappa, \zeta, \nu, \iota, \wp \in \mathcal{M}$.

Now

$$\begin{aligned} \mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) &= (|(x, y, z) - (\lambda, \kappa, \zeta)| + |(\lambda, \kappa, \zeta) - (\nu, \iota, \wp)| \\ &\quad + |(\nu, \iota, \wp) - (x, y, z)|)^2 \\ &= \left(\left| \frac{2x-4y+6z+20}{24} - \frac{3\lambda-6\kappa+9\zeta+30}{36} \right| + \left| \frac{3\lambda-6\kappa+9\zeta+30}{36} - \frac{4\nu-8\iota+12\wp+40}{48} \right| \right. \\ &\quad \left. + \left| \frac{4\nu-8\iota+12\wp+40}{48} - \frac{2x-4y+6z+20}{24} \right| \right)^2 \\ &\leq \left(\frac{1}{12} [|x - \lambda| + |\lambda - \nu| + |\nu - x|] + \frac{1}{6} [|y - \kappa| + |\kappa - \iota| + |\iota - y|] \right. \\ &\quad \left. + \frac{1}{4} [|z - \zeta| + |\zeta - \wp| + |\wp - z|] \right)^2 \\ &\leq \left(\frac{1}{4} [|x - \lambda| + |\lambda - \nu| + |\nu - x|] + \frac{1}{4} [|y - \kappa| + |\kappa - \iota| + |\iota - y|] \right. \\ &\quad \left. + \frac{1}{4} [|z - \zeta| + |\zeta - \wp| + |\wp - z|] \right)^2 \\ &\leq \frac{3}{16} [(|x - \lambda| + |\lambda - \nu| + |\nu - x|)^2 + (|y - \kappa| + |\kappa - \iota| + |\iota - y|)^2 \\ &\quad + (|z - \zeta| + |\zeta - \wp| + |\wp - z|)^2] \\ &= \frac{3}{16} [\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)] \\ &= \frac{9}{16} \cdot \frac{[\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]}{3} \\ &\leq \mathbb{K}_1 \frac{\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}{3} \\ &\quad + \mathbb{K}_2 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\ &\quad + \mathbb{K}_3 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\ &\quad + \mathbb{K}_4 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\ &\quad + \mathbb{K}_5 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\ &\quad + \mathbb{K}_6 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\ &\quad + \mathbb{K}_7 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\ &\quad + \mathbb{K}_8 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\ &\quad + \mathbb{K}_9 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \end{aligned}$$

$$\begin{aligned}
 &+ \mathbb{K}_{10} \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_{11} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_{12} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_{13} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}
 \end{aligned}$$

where $\mathbb{K}_1 = 9/16$ and $\mathbb{K}_2 = \mathbb{K}_3 = \mathbb{K}_4 = \dots = \mathbb{K}_{13} = 0$ so that $0 \leq \mathbb{K}_1 + \mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + 3(\mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7) + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13} < 1$. Thus all the conditions of Theorem 2.1 are satisfied. Therefore, \mathcal{S}, \mathcal{T} and \mathcal{R} have a unique common coupled fixed point, namely $(1, 1, 1)$.

Corollary 2.1. Let $(\mathcal{M}, \mathcal{G}_b)$ be a complete symmetric \mathcal{G}_b -metric space with parameter $s \geq 1$ and $\mathcal{S} : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow \mathcal{M}$ be a mapping such that

$$\begin{aligned}
 &\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{S}(\lambda, \kappa, \zeta), \mathcal{S}(\nu, \iota, \wp)) \tag{2.12} \\
 \leq &\mathbb{K}_1 \frac{\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}{3} \\
 &+ \mathbb{K}_2 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{S}(\lambda, \kappa, \zeta), \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_3 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{S}(\lambda, \kappa, \zeta), \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_4 \frac{\mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{S}(\lambda, \kappa, \zeta), \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_5 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_6 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_7 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_8 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_9 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_{10} \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_{11} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, \lambda, \nu)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_{12} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(y, \kappa, \iota)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)} \\
 &+ \mathbb{K}_{13} \frac{\mathcal{G}_b(\nu, \nu, \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(z, \zeta, \wp)}{1 + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}
 \end{aligned}$$

for all $x, y, z, \lambda, \kappa, \zeta, \nu, \iota, \wp \in \mathcal{M}$ and non negative real numbers $\mathbb{K}_1, \mathbb{K}_2, \mathbb{K}_3, \mathbb{K}_4, \mathbb{K}_5, \mathbb{K}_6, \mathbb{K}_7, \mathbb{K}_8, \mathbb{K}_9, \mathbb{K}_{10}, \mathbb{K}_{11}, \mathbb{K}_{12}, \mathbb{K}_{13}$ with $0 \leq \mathbb{K}_1 + \mathbb{K}_2 + \mathbb{K}_3 + \mathbb{K}_4 + 3(\mathbb{K}_5 + \mathbb{K}_6 + \mathbb{K}_7) + \mathbb{K}_8 + \mathbb{K}_9 + \mathbb{K}_{10} + \mathbb{K}_{11} + \mathbb{K}_{12} + \mathbb{K}_{13} < 1$. Then \mathcal{S} has a unique tripled fixed point in $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$.

Theorem 2.2 Let $(\mathcal{M}, \mathcal{G}_b)$ be a complete symmetric \mathcal{G}_b -metric space with parameter $s \geq 1$ and $\mathcal{S}, \mathcal{T}, \mathcal{R} : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow \mathcal{M}$ be three mappings such that

$$\begin{aligned} \mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(\lambda, \kappa, \zeta), \mathcal{R}(\nu, \iota, \wp)) &\leq \chi_1 \frac{\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}{3} \\ &+ \chi_2 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta))}{1 + s[\mathcal{G}_b(x, x, \mathcal{T}(\lambda, \kappa, \zeta)) + \mathcal{G}_b(\lambda, \lambda, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \\ &+ \chi_3 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{T}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp))}{1 + s[\mathcal{G}_b(\nu, \nu, \mathcal{T}(\lambda, \kappa, \zeta)) + \mathcal{G}_b(\lambda, \lambda, \mathcal{R}(\nu, \iota, \wp)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, c)]} \\ &+ \chi_4 \frac{\mathcal{G}_b(\nu, \nu, \mathcal{R}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, x, \mathcal{S}(x, y, z))}{1 + s[\mathcal{G}_b(\nu, \nu, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, x, \mathcal{R}(\nu, \iota, \wp)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \end{aligned} \quad (2.13)$$

for all $x, y, z, \lambda, \kappa, \zeta, \nu, \iota, \wp \in \mathcal{M}$ and non negative real numbers χ_1, χ_2, χ_3 and χ_4 with $0 \leq \chi_1 + \chi_2 + \chi_3 + \chi_4 < 1$.

Then \mathcal{S}, \mathcal{T} and \mathcal{R} have a unique common tripled fixed point in $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$.

Proof. Let x_0, y_0 and z_0 be any three elements in \mathcal{M} . We construct three sequences $\langle x_\sigma \rangle_{\sigma=1}^\infty, \langle y_\sigma \rangle_{\sigma=1}^\infty$ and $\langle z_\sigma \rangle_{\sigma=1}^\infty$ in \mathcal{M} as follows:

$$\begin{aligned} x_{3\phi+1} &= \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}), y_{3\phi+1} = \mathcal{S}(y_{3\phi}, z_{3\phi}, x_{3\phi}), z_{3\phi+1} = \mathcal{S}(z_{3\phi}, x_{3\phi}, y_{3\phi}) \\ x_{3\phi+2} &= \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}), y_{3\phi+2} = \mathcal{T}(y_{3\phi+1}, z_{3\phi+1}, x_{3\phi+1}), z_{3\phi+2} = \mathcal{T}(z_{3\phi+1}, x_{3\phi+1}, y_{3\phi+1}) \\ x_{3\phi+3} &= \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2}), y_{3\phi+3} = \mathcal{R}(y_{3\phi+2}, z_{3\phi+2}, x_{3\phi+2}), z_{3\phi+3} = \mathcal{R}(z_{3\phi+2}, x_{3\phi+2}, y_{3\phi+2}) \\ &\text{for } \phi = 0, 1, 2, 3, \dots \end{aligned}$$

Now using (2.13) with $x = x_{3\phi}, y = y_{3\phi}, z = z_{3\phi}, \lambda = x_{3\phi+1}, \kappa = y_{3\phi+1}, \zeta = z_{3\phi+1}, \nu = x_{3\phi+2}, \iota = y_{3\phi+2}$ and $\wp = z_{3\phi+2}$, we get

$$\begin{aligned} &\mathcal{G}_b(\mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}), \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}), \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \\ &\leq \chi_1 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}{3} \\ &+ \chi_2 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi}, \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi})) \cdot \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1}))}{1 + s[\mathcal{G}_b(x_{3\phi}, x_{3\phi}, \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1})) + \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi})) \\ &\quad + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\ &+ \chi_3 \frac{\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1})) \cdot \mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2}))}{1 + s[\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, \mathcal{T}(x_{3\phi+1}, y_{3\phi+1}, z_{3\phi+1})) + \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \\ &\quad + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, b) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\ &+ \chi_4 \frac{\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \cdot \mathcal{G}_b(x_{3\phi}, x_{3\phi}, \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi}))}{1 + s[\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, \mathcal{S}(x_{3\phi}, y_{3\phi}, z_{3\phi})) + \mathcal{G}_b(x_{3\phi}, x_{3\phi}, \mathcal{R}(x_{3\phi+2}, y_{3\phi+2}, z_{3\phi+2})) \\ &\quad + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\ &= \chi_1 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}{3} \\ &+ \chi_2 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi}, x_{3\phi+1}) \cdot \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, x_{3\phi+2})}{1 + s[\mathcal{G}_b(x_{3\phi}, x_{3\phi}, x_{3\phi+2}) + \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, x_{3\phi+1}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) \\ &\quad + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\ &+ \chi_3 \frac{\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, x_{3\phi+2}) \cdot \mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, x_{3\phi+3})}{1 + s[\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, x_{3\phi+2}) + \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, x_{3\phi+3}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) \\ &\quad + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \end{aligned}$$

$$\begin{aligned}
 & +\chi_4 \frac{\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, x_{3\phi+3}) \cdot \mathcal{G}_b(x_{3\phi}, x_{3\phi}, x_{3\phi+1})}{1 + s[\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, x_{3\phi+1}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi}, x_{3\phi+3}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) \\
 & \quad + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\
 \leq & \chi_1 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}{3} \\
 & +\chi_2 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) \cdot \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3})}{1 + s[\mathcal{G}_b(x_{3\phi}, x_{3\phi}, x_{3\phi+2}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) \\
 & \quad + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\
 & +\chi_3 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) \cdot \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3})}{1 + s[\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+1}, x_{3\phi+3}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) \\
 & \quad + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\
 & +\chi_4 \frac{\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) \cdot \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2})}{1 + s[\mathcal{G}_b(x_{3\phi+2}, x_{3\phi+2}, x_{3\phi+1}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi}, x_{3\phi+3}) + \mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) \\
 & \quad + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]} \\
 \leq & \chi_1 \frac{\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})}{3} \\
 & +(\chi_2 + \chi_3 + \chi_4) \cdot \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3})
 \end{aligned}$$

So that,

$$\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) \leq \frac{\frac{\chi_1}{3}}{[1 - (\chi_2 + \chi_3 + \chi_4)]} \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})] \quad (2.14)$$

Similarly,

$$\mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) \leq \frac{\frac{\chi_1}{3}}{[1 - (\chi_2 + \chi_3 + \chi_4)]} \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})] \quad (2.15)$$

and

$$\mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3}) \leq \frac{\frac{\chi_1}{3}}{[1 - (\chi_2 + \chi_3 + \chi_4)]} \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})] \quad (2.16)$$

Adding (2.14),(2.15) and (2.16),we have

$$\begin{aligned}
 & \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) + \mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) + \mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3}) \\
 & \leq \frac{\chi_1}{[1 - (\chi_2 + \chi_3 + \chi_4)]} \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) \\
 & \quad + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})].
 \end{aligned}$$

or

$$\begin{aligned}
 & \mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) + \mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) + \mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3}) \\
 & \leq h \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})].
 \end{aligned} \quad (2.17)$$

where $h = \frac{\chi_1}{[1 - (\chi_2 + \chi_3 + \chi_4)]}$ and $0 \leq h < 1$ in view of choice of χ_1, χ_2, χ_3 and χ_4 .

Also, it can be proved that

$$\begin{aligned} & \mathcal{G}_b(x_{3\phi+2}, x_{3\phi+3}, x_{3\phi+4}) + \mathcal{G}_b(y_{3\phi+2}, y_{3\phi+3}, y_{3\phi+4}) + \mathcal{G}_b(z_{3\phi+2}, z_{3\phi+3}, z_{3\phi+4}) \\ & \leq h \cdot [\mathcal{G}_b(x_{3\phi+1}, x_{3\phi+2}, x_{3\phi+3}) + \mathcal{G}_b(y_{3\phi+1}, y_{3\phi+2}, y_{3\phi+3}) + \mathcal{G}_b(z_{3\phi+1}, z_{3\phi+2}, z_{3\phi+3})] \\ & \leq h^2 \cdot [\mathcal{G}_b(x_{3\phi}, x_{3\phi+1}, x_{3\phi+2}) + \mathcal{G}_b(y_{3\phi}, y_{3\phi+1}, y_{3\phi+2}) + \mathcal{G}_b(z_{3\phi}, z_{3\phi+1}, z_{3\phi+2})]. \end{aligned}$$

Proceeding like this, we get

$$\begin{aligned} & \mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+2}) + \mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+2}) + \mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+2}) \\ & \leq h \cdot [\mathcal{G}_b(x_{\sigma-1}, x_\sigma, x_{\sigma+1}) + \mathcal{G}_b(y_{\sigma-1}, y_\sigma, y_{\sigma+1}) + \mathcal{G}_b(z_{\sigma-1}, z_\sigma, z_{\sigma+1})] \\ & \leq h^2 \cdot [\mathcal{G}_b(x_{\sigma-2}, x_{\sigma-1}, x_\sigma) + \mathcal{G}_b(y_{\sigma-2}, y_{\sigma-1}, y_\sigma) + \mathcal{G}_b(z_{\sigma-2}, z_{\sigma-1}, z_\sigma)] \\ & \leq h^\sigma \cdot [\mathcal{G}_b(x_0, x_1, x_2) + \mathcal{G}_b(y_0, y_1, y_2) + \mathcal{G}_b(z_0, z_1, z_2)], \text{ where } \sigma = 3\phi + 2. \end{aligned}$$

Let $\Delta_\sigma = \mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+2}) + \mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+2}) + \mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+2})$. Then the above inequality becomes as $\Delta_\sigma \leq h\Delta_{\sigma-1} \leq h^2\Delta_{\sigma-2} \leq \dots \leq h^\sigma\Delta_0$ for $\sigma \in \mathbb{N}$

Suppose $\xi > \sigma$. Now using repeated application of rectangle inequality of \mathcal{G}_b -metric and the inequality $\Delta_\sigma \leq h^\sigma\Delta_0$, we have

$$\begin{aligned} & \mathcal{G}_b(x_\sigma, x_\xi, x_\xi) + \mathcal{G}_b(y_\sigma, y_\xi, y_\xi) + \mathcal{G}_b(z_\sigma, z_\xi, z_\xi) \leq s[\mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+1}) + \mathcal{G}_b(x_{\sigma+1}, x_\xi, x_\xi)] \\ & \quad + s[\mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+1}) + \mathcal{G}_b(y_{\sigma+1}, y_\xi, y_\xi)] + s[\mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+1}) + \mathcal{G}_b(z_{\sigma+1}, z_\xi, z_\xi)] \\ & \leq s[\mathcal{G}_b(x_\sigma, x_{\sigma+1}, x_{\sigma+1}) + \mathcal{G}_b(y_\sigma, y_{\sigma+1}, y_{\sigma+1}) + \mathcal{G}_b(z_\sigma, z_{\sigma+1}, z_{\sigma+1})] \\ & \quad + s^2[\mathcal{G}_b(x_{\sigma+1}, x_{\sigma+2}, x_{\sigma+2}) + \mathcal{G}_b(y_{\sigma+1}, y_{\sigma+2}, y_{\sigma+2}) + \mathcal{G}_b(z_{\sigma+1}, z_{\sigma+2}, z_{\sigma+2})] \\ & \quad + \dots + s^{m-n}[\mathcal{G}_b(x_{\xi-1}, x_{\xi-1}, x_m) + \mathcal{G}_b(y_{\xi-1}, y_{\xi-1}, y_\xi) + \mathcal{G}_b(z_{\xi-1}, z_{\xi-1}, z_\xi)] \\ & = s\Delta_n + s^2\Delta_{\sigma+1} + s^3\Delta_{\sigma+2} + \dots + s^{\xi-\sigma}\Delta_{\xi-1} \\ & \leq [sh^\sigma + s^2h^{\sigma+1} + \dots + s^{\xi-\sigma}h^{\xi-1}]\Delta_0 \\ & \leq sh^\sigma \cdot \frac{1}{1-h}\Delta_0 \text{ for } \xi > \sigma \end{aligned}$$

or

$$\mathcal{G}_b(x_\sigma, x_\xi, x_\xi) + \mathcal{G}_b(y_\sigma, y_\xi, y_\xi) + \mathcal{G}_b(z_\sigma, z_\xi, z_\xi) \leq s \cdot h^n \cdot \frac{1}{1-h}\Delta_0 \text{ for } \xi > \sigma. \quad (2.18)$$

Since $0 \leq h < 1, h^\sigma \rightarrow 0$ as $\sigma \rightarrow \infty$.

Now applying limit as $\sigma \rightarrow \infty$ with $\xi > \sigma$ in the inequality (2.18), we have

$\mathcal{G}_b(x_\sigma, x_\xi, x_\xi) + \mathcal{G}_b(y_\sigma, y_\xi, y_\xi) + \mathcal{G}_b(z_\sigma, z_\xi, z_\xi) \leq 0$ which follows that $\langle x_\sigma \rangle_{\sigma=1}^\infty, \langle y_\sigma \rangle_{\sigma=1}^\infty$ and $\langle z_\sigma \rangle_{\sigma=1}^\infty$ are \mathcal{G}_b -Cauchy sequences in \mathcal{M} .

Since $(\mathcal{M}, \mathcal{G}_b)$ is a complete \mathcal{G}_b -metric space, there exist $x, y, z \in \mathcal{M}$ such that $x_\sigma \rightarrow x, y_\sigma \rightarrow y$ and $z_\sigma \rightarrow z$.

Now we prove that (x, y, z) is a tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} .

Again using (2.13) with $x = x_\sigma, y = y_\sigma, z = z_\sigma, \lambda = x, \kappa = y, \zeta = z, \nu = x, \iota = y$ and $\wp = z$, we get

$$\mathcal{G}_b(x, \mathcal{S}(x, y, z), \mathcal{S}(x, y, z)) \leq s[\mathcal{G}_b(x, x_{\sigma+1}, x_{\sigma+1}) + \mathcal{G}_b(x_{\sigma+1}, \mathcal{S}(x, y, z), \mathcal{S}(x, y, z))] \quad (2.19)$$

$$\leq s\mathcal{G}_b(x, x_{\sigma+1}, x_{\sigma+1}) + s\left[\chi_1 \frac{\mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)}{3}\right] \quad (2.20)$$

$$+ \chi_2 \frac{\mathcal{G}_b(x_\sigma, x_\sigma, \mathcal{S}(x_\sigma, y_\sigma, z_\sigma)) \cdot \mathcal{G}_b(x, x, \mathcal{S}(x, y, z))}{1 + s[\mathcal{G}_b(x_\sigma, x_\sigma, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, x, \mathcal{S}(x_\sigma, y_\sigma, z_\sigma)) + \mathcal{G}_b(x_\sigma, x, x) + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)]}$$

$$\begin{aligned}
 & +\chi_3 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x, x, \mathcal{S}(x, y, z))}{1 + s[\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x_\sigma, x, x) \\
 & \qquad \qquad \qquad + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)]} \\
 & +\chi_4 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(x_\sigma, x_\sigma, \mathcal{S}(x_\sigma, y_\sigma, z_\sigma))}{1 + s[\mathcal{G}_b(x, x, \mathcal{S}(x_\sigma, y_\sigma, z_\sigma)) + \mathcal{G}_b(x_\sigma, x_\sigma, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x_\sigma, x, x) \\
 & \qquad \qquad \qquad + \mathcal{G}_b(y_\sigma, y, y) + \mathcal{G}_b(z_\sigma, z, z)]}
 \end{aligned}$$

Since $x_\sigma \rightarrow x, y_\sigma \rightarrow y$ and $z_\sigma \rightarrow z$, from the inequality(2.19) it follows that

$(1 - s\chi_3)\mathcal{G}_b(x, \mathcal{S}(x, y, z), \mathcal{S}(x, y, z)) \leq 0$ which implies $\mathcal{S}(x, y, z) = x$.

Similarly, it can be shown that $\mathcal{S}(y, x, z) = y, \mathcal{S}(z, x, y) = z, \mathcal{T}(x, y, z) = x, \mathcal{T}(y, x, z) = y, \mathcal{T}(z, x, y) = z, \mathcal{R}(x, y, z) = x, \mathcal{R}(y, x, z) = y$ and $\mathcal{R}(z, x, y) = z$

That is (x, y, z) is a common tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} .

Uniqueness:

Suppose (l, m, n) is another common tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} .

That is, $\mathcal{S}(l, m, n) = \mathcal{T}(l, m, n) = \mathcal{R}(l, m, n) = l, \mathcal{S}(m, l, n) = \mathcal{T}(m, l, n) = \mathcal{R}(m, l, n) = m$ and $\mathcal{S}(n, l, m) = \mathcal{T}(n, l, m) = \mathcal{R}(n, l, m) = n$

Using inequality(2.13),we have

$$\begin{aligned}
 & \mathcal{G}_b(x, l, l) = \mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{T}(l, m, n), \mathcal{R}(l, m, n)) \\
 & \leq \chi_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} \\
 & +\chi_2 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(l, l, \mathcal{T}(l, m, n))}{1 + s[\mathcal{G}_b(x, x, \mathcal{T}(l, m, n)) + \mathcal{G}_b(l, l, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)]} \\
 & +\chi_3 \frac{\mathcal{G}_b(l, l, \mathcal{T}(l, m, n)) \cdot \mathcal{G}_b(l, l, \mathcal{R}(l, m, n))}{1 + s[\mathcal{G}_b(l, l, \mathcal{T}(l, m, n)) + \mathcal{G}_b(l, l, \mathcal{R}(l, m, n)) + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)]} \\
 & +\chi_4 \frac{\mathcal{G}_b(l, l, \mathcal{R}(l, m, n)) \cdot \mathcal{G}_b(x, x, \mathcal{S}(x, y, z))}{1 + s[\mathcal{G}_b(l, l, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, x, \mathcal{R}(l, m, n)) + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)]} \\
 & = \chi_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} \\
 & +\chi_2 \frac{\mathcal{G}_b(x, x, x) \cdot \mathcal{G}_b(l, l, l)}{1 + s[\mathcal{G}_b(x, x, l) + \mathcal{G}_b(l, l, x) + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)]} \\
 & +\chi_3 \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(l, l, l)}{1 + s[\mathcal{G}_b(l, l, l) + \mathcal{G}_b(l, l, l) + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)]} \\
 & +\chi_4 \frac{\mathcal{G}_b(l, l, l) \cdot \mathcal{G}_b(x, x, x)}{1 + s[\mathcal{G}_b(l, l, x) + \mathcal{G}_b(x, x, l) + \mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)]}
 \end{aligned}$$

which implies

$$\mathcal{G}_b(x, l, l) \leq \chi_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} \tag{2.21}$$

Similarly

$$\mathcal{G}_b(y, m, m) \leq \chi_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} \tag{2.22}$$

and

$$\mathcal{G}_b(z, n, n) \leq \chi_1 \frac{\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n)}{3} \tag{2.23}$$

Adding (2.21),(2.22) and (2.23), we get

$$(1 - \chi_1)\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n) \leq 0 \tag{2.24}$$

Since $\chi_1 < 1$, we have $\mathcal{G}_b(x, l, l) + \mathcal{G}_b(y, m, m) + \mathcal{G}_b(z, n, n) = 0$ which implies that $x = l, y = m$ and $z = n$. Thus, (x, y, z) is a unique common tripled fixed point of \mathcal{S}, \mathcal{T} and \mathcal{R} in $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$. □

Corollary 2.2. Let $(\mathcal{M}, \mathcal{G}_b)$ be a complete symmetric \mathcal{G}_b -metric space with parameter $s \geq 1$ and $\mathcal{S} : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow \mathcal{M}$ be a mapping such that

$$\begin{aligned} & \mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{S}(\lambda, \kappa, \zeta), \mathcal{S}(\nu, \iota, \wp)) \\ & \leq \chi_1 \frac{\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}{3} \\ & + \chi_2 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\lambda, \kappa, \zeta))}{1 + s[\mathcal{G}_b(x, x, \mathcal{S}(\lambda, \kappa, \zeta)) + \mathcal{G}_b(\lambda, \lambda, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \\ & + \chi_3 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(\nu, \nu, \mathcal{S}(\nu, \iota, \wp))}{1 + s[\mathcal{G}_b(\nu, \nu, \mathcal{S}(\lambda, \kappa, \zeta)) + \mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\nu, \iota, \wp)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \\ & + \chi_4 \frac{\mathcal{G}_b(\nu, \nu, \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, x, \mathcal{S}(x, y, z))}{1 + s[\mathcal{G}_b(\nu, \nu, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, x, \mathcal{S}(\nu, \iota, \wp)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \end{aligned} \quad (2.25)$$

for all $x, y, z, \lambda, \kappa, \zeta, \nu, \iota, \wp \in X$ and non negative real numbers χ_1, χ_2, χ_3 and χ_4 with $0 \leq \chi_1 + \chi_2 + \chi_3 + \chi_4 < 1$.

Then \mathcal{S} has a unique tripled fixed point in $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$.

The following example illustrates the Corollary 2.2

Example 2.2. Let $\mathcal{M} = [0, 1]$. Define $\mathcal{G}_b : \mathcal{M} \times \mathcal{M} \times \mathcal{M} \rightarrow [0, \infty)$ by $\mathcal{G}_b(\alpha, \beta, \gamma) = (|\alpha - \beta| + |\beta - \gamma| + |\gamma - \alpha|)^2$, where $s = 2$. Clearly, $(\mathcal{M}, \mathcal{G}_b)$ is a complete \mathcal{G}_b -metric space.

Let $\mathcal{S}(\alpha, \beta, \gamma) = \frac{\alpha + 2\beta + 3\gamma}{18}$ for $\alpha, \beta, \gamma \in \mathcal{M}$.

Now

$$\begin{aligned} & \mathcal{G}_b(\mathcal{S}(x, y, z), \mathcal{S}(\lambda, \kappa, \zeta), \mathcal{S}(\nu, \iota, \wp)) = (|\mathcal{S}(x, y, z) - \mathcal{S}(\lambda, \kappa, \zeta)| + |\mathcal{S}(\lambda, \kappa, \zeta) - \mathcal{S}(\nu, \iota, \wp)| \\ & \quad + |\mathcal{S}(\nu, \iota, \wp) - \mathcal{S}(x, y, z)|)^2 \\ & = \left(\left| \frac{x+2y+3z}{18} - \frac{\lambda+2\kappa+3\zeta}{18} \right| + \left| \frac{\lambda+2\kappa+3\zeta}{18} - \frac{\nu+2\iota+3\wp}{18} \right| + \left| \frac{\nu+2\iota+3\wp}{18} - \frac{x+2y+3z}{18} \right| \right)^2 \\ & \leq \left(\frac{1}{18} [|x - \lambda| + |\lambda - \nu| + |\nu - x|] + \frac{1}{9} [|y - \kappa| + |\kappa - \iota| + |\iota - y|] \right. \\ & \quad \left. + \frac{1}{6} [|z - \zeta| + |\zeta - \wp| + |\wp - z|] \right)^2 \\ & \leq \left(\frac{1}{6} [|x - \lambda| + |\lambda - \nu| + |\nu - x|] + \frac{1}{6} [|y - \kappa| + |\kappa - \iota| + |\iota - y|] \right. \\ & \quad \left. + \frac{1}{6} [|z - \zeta| + |\zeta - \wp| + |\wp - z|] \right)^2 \\ & \leq \frac{1}{12} [(|x - \lambda| + |\lambda - \nu| + |\nu - x|)^2 + (|y - \kappa| + |\kappa - \iota| + |\iota - y|)^2 \\ & \quad + (|z - \zeta| + |\zeta - \wp| + |\wp - z|)^2] \\ & = \frac{1}{12} [\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)] \\ & = \frac{1}{4} \cdot \frac{[\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]}{3} \\ & \leq \chi_1 \frac{\mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)}{3} \\ & + \chi_2 \frac{\mathcal{G}_b(x, x, \mathcal{S}(x, y, z)) \cdot \mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\lambda, \kappa, \zeta))}{1 + s[\mathcal{G}_b(x, x, \mathcal{S}(\lambda, \kappa, \zeta)) + \mathcal{G}_b(\lambda, \lambda, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \\ & + \chi_3 \frac{\mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\lambda, \kappa, \zeta)) \cdot \mathcal{G}_b(\nu, \nu, \mathcal{S}(\nu, \iota, \wp))}{1 + s[\mathcal{G}_b(\nu, \nu, \mathcal{S}(\lambda, \kappa, \zeta)) + \mathcal{G}_b(\lambda, \lambda, \mathcal{S}(\nu, \iota, \wp)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \\ & + \chi_4 \frac{\mathcal{G}_b(\nu, \nu, \mathcal{S}(\nu, \iota, \wp)) \cdot \mathcal{G}_b(x, x, \mathcal{S}(x, y, z))}{1 + s[\mathcal{G}_b(\nu, \nu, \mathcal{S}(x, y, z)) + \mathcal{G}_b(x, x, \mathcal{S}(\nu, \iota, \wp)) + \mathcal{G}_b(x, \lambda, \nu) + \mathcal{G}_b(y, \kappa, \iota) + \mathcal{G}_b(z, \zeta, \wp)]} \end{aligned}$$

where $\chi_1 = 1/4$ and $\chi_2 = 0, \chi_3 = 0, \chi_4 = 0$ such that $0 \leq \chi_1 + \chi_2 + \chi_3 + \chi_4 < 1$. Hence all the conditions of Corollary 2.2 are satisfied. Thus, \mathcal{S} has a unique tripled fixed point $(0, 0, 0)$ in $\mathcal{M} \times \mathcal{M} \times \mathcal{M}$.

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